

Sweep



Sweeps the shaft of a RC servo motor back and forth across 180 degrees. This example makes use of the Arduino servo library.

★ Specification

Please view SG90Servo-datasheet.pdf. Path: \Public_materials\Datasheet\ SG90Servo-datasheet.pdf

* Pin definition PWM=Orange (_____) Vcc = Red (+) Ground=Brown (-)

★ Hardware required

Material diagram	Material name	Number
	9g Servo	1
0	USB Cable	1
	UNO R3	1
	Breadboard	1
	Jumper wires	Several



Connection

★ Schematic





★ Sample code

```
Note: sample code under the Sample code folder
#include <Servo.h>
Servo myservo; // create servo object to control a servo
// twelve servo objects can be created on most boards
int pos = 0;
void setup() {
     myservo.attach(9); // attaches the servo on pin 9 to the servo object
}
void loop() {
for (pos = 0; pos <= 180; pos += 1) { // goes from 0 degrees to 180 degrees
     // in steps of 1 degree
     myservo.write(pos);
     delay(15);
}
for (pos = 180; pos >= 0; pos -= 1) { // goes from 180 degrees to 0 degrees
     myservo.write(pos);
     delay(15);
     }
                               }
```



★ Example picture



6.



★ Language reference

null

★ Application effect

You will see the servo motor turning 180 degrees back and forth.

About Miuzei:

Miuzei found in 2011, which is a professional manufacturer and exporter that concerned with open-source hardware research & product development, We have more than hundred engineers devote to developing open source hardware like Arduino, Raspberry pi, 3d printers, robots.

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